

CS6015: Linear Algebra and Random Processes

Course Instructor : Prashanth L.A.

Exam - 1: Solutions

I. Multiple Choice Questions (Answer any eight)

- Let V be a vector space with dimension 12. Let S be a subset of V which is linearly independent and has 11 vectors. Which of the following is FALSE?
 - There must exist a linearly independent subset S_1 of V such that $S \subsetneq S_1$ and S_1 is not a basis for V .
 - Every nonempty subset S_1 of S is linearly independent.
 - There must exist a linearly dependent subset S_1 of V such that $S \subsetneq S_1$.
 - Dimension of $\text{span}(S) < \text{dimension of } V$.

Solution: (a)

- Let W be a subspace of \mathbb{R}^n and W^\perp denote its orthogonal complement. If W_1 is subspace of \mathbb{R}^n such that if $x \in W_1$, then $x^\top u = 0$, for all $u \in W^\perp$. Then,
 - $\dim W_1^\perp \leq \dim W^\perp$
 - $\dim W_1^\perp \leq \dim W$
 - $\dim W_1^\perp \geq \dim W^\perp$
 - $\dim W_1^\perp \geq \dim W$

Solution: (c)

- Let A be a 5×5 matrix with real entries and $x \neq 0$. Then, the vectors $x, Ax, A^2x, A^3x, A^4x, A^5x$ are
 - linearly independent
 - linearly dependent
 - linearly independent if and only if A is symmetric
 - linear dependence/independence cannot be determined from given data

Solution: (b)

- Let A, B be two complex $n \times n$ matrices that are Hermitian and

$$C_1 = A + B, C_2 = iA + (2 + 3i)B, \text{ and } C_3 = AB.$$

Then, among C_1, C_2, C_3 , which is/are Hermitian?

- Only C_1
- Only C_2
- Only C_3
- All of them

Solution: (a)

- If A is a 10×8 real matrix with rank 8, then
 - there exists at least one $b \in \mathbb{R}^{10}$ for which the system $Ax = b$ has infinite number of least square solutions.
 - for every $b \in \mathbb{R}^{10}$, the system $Ax = b$ has infinite number of solutions.
 - there exists at least one $b \in \mathbb{R}^{10}$ such that the system $Ax = b$ has a unique least square solution.
 - for every $b \in \mathbb{R}^{10}$, the system $Ax = b$ has a unique solution.

Solution: (c)

6. Let A be a Hermitian matrix. Then, which of the following statements is false?

1. The diagonal entries of A are all real.
2. There exists a unitary U such that U^*AU is a diagonal matrix.
3. If $A^3 = I$, then $A = I$.
4. If $A^2 = I$, then $A = I$.

Solution: (d)

7. Let A be a complex $n \times n$ matrix. Let $\lambda_1, \lambda_2, \lambda_3$ be three distinct eigenvalues of A , with corresponding eigenvectors z_1, z_2, z_3 . Then, which of the following statements is false?

1. $z_1 + z_2, z_1 - z_2, z_3$ are linearly independent.
2. z_1, z_2, z_3 are linearly independent.
3. $z_1, z_1 + z_2, z_1 + z_2 + z_3$ are linearly independent.
4. z_1, z_2, z_3 are linearly independent if and only if A is diagonalizable.

Solution: (d)

8. Let A be a $n \times n$ real matrix. Then, which of the following statements is true?

1. If the eigenvalues of A are $\lambda_1, \dots, \lambda_n$, then A is similar to a diagonal matrix with $\lambda_1, \dots, \lambda_n$ along the diagonal.
2. If $\text{rank}(A) = r$, then A has r non-zero eigenvalues.
3. If $A^k = 0$ for some $k > 0$, then $\text{trace}(A) = 0$.
4. If A has a repeated eigenvalue, then A is not diagonalizable.

Solution: (c)

9. Let P_1 and P_2 be $n \times n$ projection matrices. Then, which of the following statements is false?

1. $P_1(P_1 - P_2)^2 = (P_1 - P_2)^2P_1$ and $P_1(P_1 - P_2)^2 = (P_1 - P_2)^2P_1$.
2. Each eigenvalue of P_1 and P_2 is either 1 or 0.
3. If P_1 and P_2 have the same rank, then they are similar.
4. $\text{rank}(P_1) + \text{rank}(P_1 - I) \neq \text{rank}(P_2) + \text{rank}(P_2 - I)$.

Solution: (d)

II. True or False? (Answer any eight)

1. In \mathbb{R}^9 , we can find a subspace W such that $\dim W = \dim W^\perp$.

Solution: False.

2. Let A and B be $n \times n$ real matrices. Then, $\text{rank}(A + B) \leq \text{rank}(A) + \text{rank}(B)$.

Solution: True.

3. If A is a $n \times n$ complex matrix with n orthonormal eigenvectors, then A is Hermitian.

Solution: False.

4. For any $a, b, c, d, e, f, g, h, i \in \mathbb{R}$, $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$, $B = \begin{bmatrix} e & d & f \\ b & a & c \\ h & g & i \end{bmatrix}$ are similar.

Solution: True.

5. An $n \times n$ real matrix A is invertible if and only if the span of the rows of A is \mathbb{R}^n .

Solution: True.

6. The null space of A is equal to the null space of $A^T A$.

Solution: True.

7. Let Q be a matrix with orthonormal columns. Then $QQ^T = I$.

Solution: False.

8. Consider the vector space \mathcal{M} of real 4×4 matrices. Then, the set of all invertible 4×4 matrices is a subspace of \mathcal{M} .

Solution: False.

9. Let A, B, C, D be square matrices of the same size. Then, $\begin{vmatrix} A & B \\ C & D \end{vmatrix} = \begin{vmatrix} D & C \\ B & A \end{vmatrix}$.

Solution: True.

10. If M and N are two subspaces of a vector space V and if every vector in V belongs either to M or to N (or both), then either $M = V$ or $N = V$ (or both).

Solution: True.

III. Problems that require detailed solutions (Answer any four)

1. Let $A = \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 1 & 2 & 2 & 2 & 3 \\ -1 & -2 & 0 & 2 & 3 \end{bmatrix}$. (3+2+3+2 marks)

- (a) Solve $Ax = 0$ and characterize the null space through its basis.
 (b) What is the rank of A ? What are the dimensions of the column space, row space and left null space of A ?

(c) Find the complete solution of $Ax = b$, where $b = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$.

(d) Find the conditions on b_1, b_2, b_3 that ensure $Ax = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ has a solution.

Solution:

- (a) Applying Gaussian elimination to the matrix A , we obtain

$$R = \begin{bmatrix} 1 & 2 & 0 & -2 & -3 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

There are two pivot variables and three free ones. Setting the free variables to $(1, 0, 0)$, $(0, 1, 0)$ and $(0, 0, 1)$ and calculating the pivot variable values gives us the following three vectors that form a basis for null space of A :

$$\begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}. \tag{1}$$

- (b) Two pivot columns in R imply $\text{rank}(A) = 2$. The dimensions of the column space, row space and left null space of A are 2, 2 and 1, respectively.

- (c) It is easy to see that $x_p = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ satisfies $Ax_p = b$. For the complete solution add any linear combination of the vectors in (1) to x_p .

- (d) Performing Gaussian elimination to the augmented matrix $[A : b]$, we obtain $[R : d]$, where $\begin{bmatrix} 2b_1 - b_2 \\ b_2 - b_1 \\ 2b_1 - b_2 + b_3 \end{bmatrix}$. The last row of R is zero, implying $2b_1 - b_2 + b_3 = 0$ to ensure $Ax = b$ has a solution.

2. Let W be a subspace of \mathbb{R}^5 defined as

$$W = \left\{ x \in \mathbb{R}^5 \mid x = \begin{pmatrix} \alpha \\ \beta \\ \alpha + \beta \\ \alpha - \beta \\ \alpha + \beta \end{pmatrix}, \text{ where } \alpha, \beta \in \mathbb{R} \right\}.$$

Answer the following:

(3+5+2 marks)

- (a) Find a basis for W .

- (b) Apply Gram-Schmidt procedure to the basis computed in the part above to get an orthonormal basis for W .
- (c) Find the dimensions of W and W^\perp .

Solution:

$$(a) \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}.$$

$$(b) \text{ Starting with first basis vector, Gram-Schmidt would give } \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{60}} \begin{bmatrix} -1 \\ 4 \\ 3 \\ -5 \\ 3 \end{bmatrix}.$$

Starting with the second basis vector, the orthonormal basis would come out as

$$\frac{1}{2} \begin{bmatrix} 0 \\ 1 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{60}} \begin{bmatrix} 4 \\ -1 \\ 3 \\ 5 \\ 3 \end{bmatrix}.$$

(c) From part (a), dimension of W is 2, implying dimension of W^\perp is 3.

3. Let $A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ Answer the following: (8+2 marks)

(a) Given that A has an eigenvalue 1 with corresponding eigenvector $x_1 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$, find the Schur decomposition of A , i.e., find a matrix P with orthonormal columns such that $P^T A P$ is upper-triangular.

(b) Is A diagonalizable? Justify your answer.

[(a)]

Solution:

(a) Any vector of the form $\begin{bmatrix} \alpha \\ -2\alpha \\ \beta \end{bmatrix}$, $\alpha, \beta \in \mathbb{R}$ is orthogonal to x_1 .

Letting $x_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$, $x_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, we obtain an orthonormal basis $\{x_1, x_2, x_3\}$.

Set P to be a matrix with x_1, x_2 and x_3 as its columns. Then,

$$P^T A P = \begin{bmatrix} 1 & 1 & \frac{2}{\sqrt{5}} \\ 0 & -1 & \frac{1}{\sqrt{5}} \\ 0 & 0 & 1 \end{bmatrix}.$$

(b) A is a real matrix, so $A^* = A^T$. Notice that $AA^T \neq A^T A$. Thus, A is not a normal matrix and hence, not diagonalizable.

4. Let $A = \begin{bmatrix} \sqrt{2} & 1 \\ 0 & \sqrt{2} \end{bmatrix}$. Answer the following: (3+5+2 marks)

- (a) Find all eigenvectors of A . Is A diagonalizable, i.e., does there exist an invertible S such that $S^{-1}AS$ is diagonal? Justify your answer.
- (b) Compute the SVD of A , i.e., find Q_1, Σ, Q_2 such that $A = Q_1 \Sigma Q_2^T$, where Q_1, Q_2 orthogonal and Σ is a diagonal matrix with non-negative entries along the diagonal.
- (c) Find a matrix B that is similar to A , but not the same as A .

Solution:

(a) A has eigenvalue $\sqrt{2}$ repeated twice. Since $A - \sqrt{2}I = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$, we have that $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is an eigenvector for A and there aren't any more independent ones. Hence, A is not diagonalizable.

(b) $A^T A = \begin{bmatrix} 2 & \sqrt{2} \\ \sqrt{2} & 3 \end{bmatrix}$ has characteristic polynomial $(\lambda - 4)(\lambda - 1)$. Thus, the singular values are $\sigma_1 = \sqrt{4} = 2$ and $\sigma_2 = \sqrt{1} = 1$ and hence $\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$. Next, we find the eigenvectors of $A^T A$. Observe that $A^T A - 4I = \begin{bmatrix} -2 & \sqrt{2} \\ \sqrt{2} & -1 \end{bmatrix}$ and hence, $\begin{bmatrix} 1 \\ \sqrt{2} \end{bmatrix}$ is an eigenvector. Normalizing, we get $u_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ \sqrt{2} \end{bmatrix}$. Along similar lines, $u_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} \sqrt{2} \\ -1 \end{bmatrix}$ is another independent eigenvector for the null space of $A^T A - I$. These eigenvectors go into the Q_2 matrix, i.e., $Q_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 & \sqrt{2} \\ \sqrt{2} & -1 \end{bmatrix}$.

Suppose the vectors v_1 and v_2 are the columns of the matrix Q_1 . Then, $\sigma_1 v_1 = Au_1$ and $\sigma_2 v_2 = Au_2$, leading to $v_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} \sqrt{2} \\ 1 \end{bmatrix}$ and $v_2 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ -\sqrt{2} \end{bmatrix}$. Hence,

$$A = \underbrace{\left(\frac{1}{\sqrt{3}} \begin{bmatrix} \sqrt{2} & 1 \\ 1 & -\sqrt{2} \end{bmatrix} \right)}_{Q_1} \underbrace{\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}}_{\Sigma} \underbrace{\left(\frac{1}{\sqrt{3}} \begin{bmatrix} 1 & \sqrt{2} \\ \sqrt{2} & -1 \end{bmatrix} \right)^T}_{Q_2^T}.$$

(c) Take any invertible matrix S and set $B = SAS^{-1}$.

5. The following information about a 5×4 real matrix A is available:

- The characteristic polynomial of $A^T A$ is $(\lambda - 9)(\lambda - 4)\lambda^2$.

• $q_1 = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $q_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ are the eigenvectors corresponding to $\lambda_1 = 9$ and $\lambda_2 = 4$ of $A^T A$.

• $Aq_1 = \sqrt{3} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $Aq_2 = \sqrt{2} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

Using the above information,

(8 + 2 marks)

- (a) find the matrix A .
- (b) find a basis for null space of A .

Solution:

- (a) From the characteristic polynomial of $A^T A$, the singular values can be read off as $\sigma_1 = \sqrt{9} = 3$ and $\sigma_2 = \sqrt{4} = 2$. The full-rank SVD of A would be of the form

$$A = \sigma_1 v_1 q_1^T + \sigma_2 v_2 q_2^T.$$

To find v_1, v_2 , observe that $\sigma_1 v_1 = A q_1$ and $\sigma_2 v_2 = A q_2$, leading to

$$\begin{aligned} A &= A q_1 q_1^T + A q_2 q_2^T \\ &= \sqrt{3} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} \frac{1}{\sqrt{3}} [1 \ 1 \ 1 \ 0] + \sqrt{2} \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \frac{1}{\sqrt{2}} [1 \ -1 \ 0 \ 0] \\ &= \begin{bmatrix} 2 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

- (b) Extend q_1, q_2 to an orthonormal basis of \mathbb{R}^4 . For this, observe that the set

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is an orthogonal set of vectors.}$$

Normalizing, we obtain, $\{q_1, q_2, q_3, q_4\}$, where $q_3 = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ 1 \\ -2 \\ 0 \end{bmatrix}$ and $q_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$.

Then, the set $\{q_3, q_4\}$ would be a basis for the null space of A (Why?).